



Connections:

- A = LH Throttle Channel
- B = RH Throttle Channel
- C = MultiProp decoder K1
- D = LH Tx sticks Side-to-Side (Controls thruster speed & direction)
- E = Rx Rudder Channel (use Y lead with steering servo)
- F = Multiprop decoder K2
- G = Anchor Winch Motor

*Note: Spare switched output from P91 could be used for 1 x